InvenSense MPU-6050

June 2012

WHO\_AM\_I : 68, error = 0

PWR\_MGMT\_2 : 0, error = 0

MPU-6050

Read accel, temp and gyro, error = 0

accel x,y,z: 2020, 652, 15708

temperature: 22.576 degrees Celsius

gyro x,y,z : 180, -87, 9,

MPU-6050

Read accel, temp and gyro, error = 0

accel x,y,z: 2068, 708, 15596

temperature: 22.529 degrees Celsius

gyro x,y,z : 194, -83, -4,

MPU-6050

Read accel, temp and gyro, error = 0

accel x,y,z: 2148, 692, 15716

temperature: 22.435 degrees Celsius

gyro x,y,z : 211, -102, 13,

MPU-6050

Read accel, temp and gyro, error = 0

accel x,y,z: 2056, 792, 15648

temperature: 22.529 degrees Celsius

gyro x,y,z : 206, -87, 6,

MPU-6050

Read accel, temp and gyro, error = 0

accel x,y,z: 2008, 700, 15704

temperature: 22.576 degrees Celsius

gyro x,y,z : 200, -78, 10,

MPU-6050

Read accel, temp and gyro, error = 0

accel x,y,z: 1968, 788, 15712

temperature: 22.529 degrees Celsius

gyro x,y,z : 205, -64, 19,

MPU-6050

Read accel, temp and gyro, error = 0

accel x,y,z: 1996, 696, 15664

temperature: 22.624 degrees Celsius

gyro x,y,z : 183, -80, 25,

MPU-6050

Read accel, temp and gyro, error = 0

accel x,y,z: 2024, 744, 15724

temperature: 22.529 degrees Celsius

gyro x,y,z : 201, -91, 4,

MPU-6050

Read accel, temp and gyro, error = 0

accel x,y,z: 2012, 664, 15664

temperature: 22.576 degrees Celsius

gyro x,y,z : 192, -94, 4,

MPU-6050

Read accel, temp and gyro, error = 0

accel x,y,z: 2076, 860, 15712

temperature: 22.482 degrees Celsius

gyro x,y,z : 199, -104, 54,

MPU-6050

Read accel, temp and gyro, error = 0

accel x,y,z: 2096, 648, 15720

temperature: 22.435 degrees Celsius

gyro x,y,z : 208, -95, 12,

MPU-6050

Read accel, temp and gyro, error = 0

accel x,y,z: 2056, 740, 15712

temperature: 22.529 degrees Celsius

gyro x,y,z : 178, -80, 35,

MPU-6050

Read accel, temp and gyro, error = 0

accel x,y,z: 2012, 628, 15756

temperature: 22.529 degrees Celsius

gyro x,y,z : 218, -109, 33,