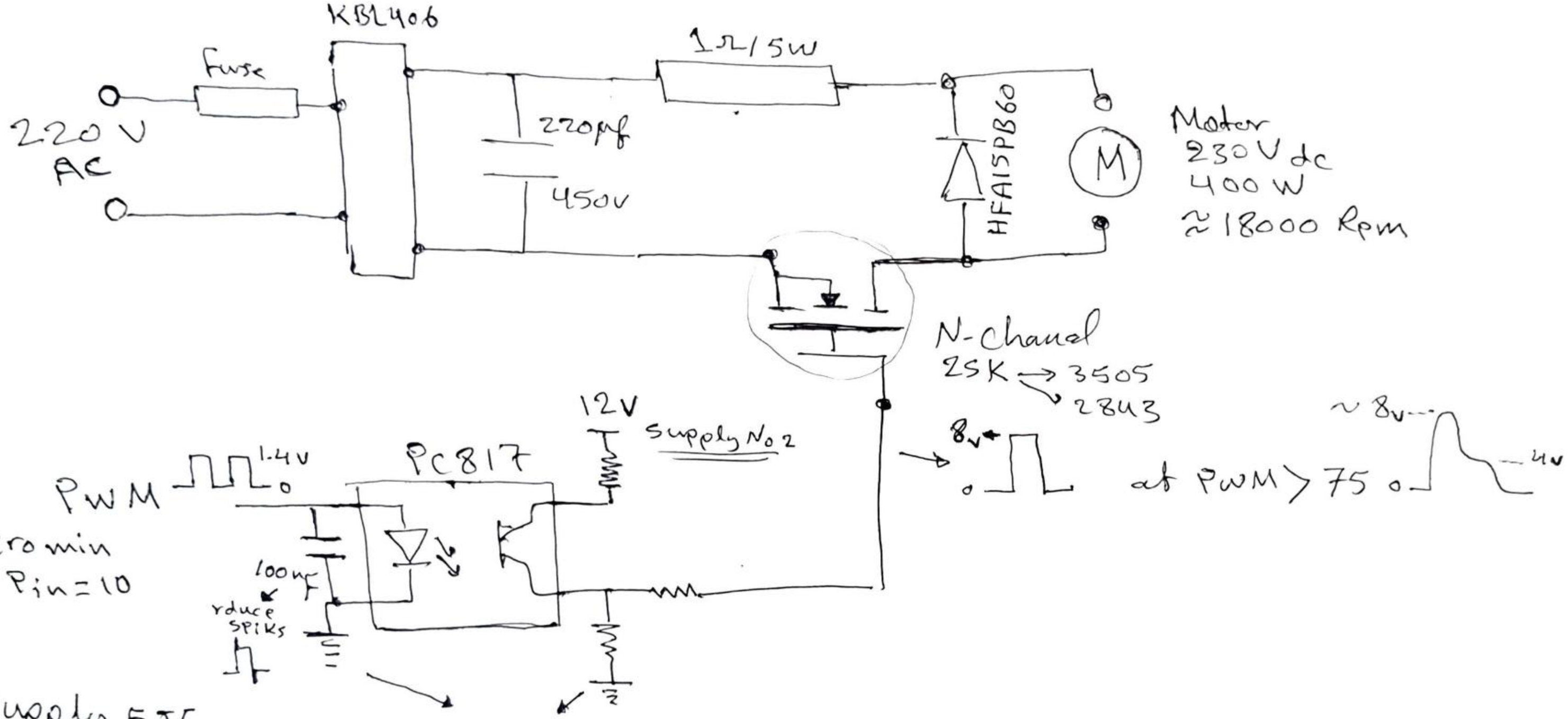

*Speed sensor module
using LM393

* Ferrite on each terminal of the Motor (toroids (rings), cylindrical sleeves, and clamp-on).

* 100nF Ceramic Cap. parallel to Motor lead.

Contral throug Nextion and Arduino code

Nextion contro time, PWM value, while promi. measur speed and send the vale to Nextion

Scanned by TapScanner